BMI 206

Structure Prediction Lab

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Why Protein Structure Prediction?

	Y 2016		
Sequences	70,650,000		
Structures	128,000		

- We have an experimentally determined atomic structure for less than 1% of the known protein sequences (and this gets worse every year).
- For assemblies of multiple proteins, even less is known.

Structural biology: Maximize accuracy, resolution, completeness, and efficiency of the structural coverage of macromolecular assemblies

Motivation: Models will allow us to understand how machines work, how they evolved, how they can be controlled, modified, and perhaps even designed.



ATP synthase nuclear pore complex

GroEL chaperonin

ribosome

structures are yet to be characterized, involved in a few hundred core biological processes.

Integrative Structural Biology

for maximizing accuracy, resolution, completeness, and efficiency of structure determination

Use structural information from any

source: measurement, first principles, rules;

resolution: low or high resolution

to obtain the set of all models that are consistent with it.



					Vilality V	
X-ray	NMR	2D & single particle	electron	immuno-	chemical	affinity purification
crystallography	spectroscopy	electron microscopy	tomography	electron microscopy	cross-linking	mass spectroscopy
subunit structure	subunit structure				subunit structure	
subunit shape	subunit shape	subunit shape	subunit shape			
subunit-subunit contact	subunit-subunit contact	subunit-subunit contact	subunit-subunit contact		subunit-subunit contact	subunit-subunit contact
subunit proximity	subunit proternity	subunit proximity	subunit proximity	subunit proximity	subunit proximity	subunit proximity
assambly symmetry	assembly symmetry	assembly symmetry	assembly symmetry	assembly symmetry		
assembly shace	assembly shape	assembly shape	assembly shape	and a state of a state		
assembly structure	assembly structure					
FRET	site-directed	veast two-hybrid	gene/protein	MGFLIKRGFGHGARWTG.	computational	bioinformatics
	mutagenesis	system	arrays	prediction subunit structure subunit shape	docking	
subunit-subunit contact subunit proximity	subunit-subunit contact	subunit-subunit contact subunit proximity	subunit-subunit contact subunit proximity		subunit-subunit contact	Subunit-subunit contact
				1		

Sali A, Earnest T, Glaeser R, Baumeister W. From words to literature in structural proteomics. *Nature* 422, 216-225, 2003. Ward A, Sali A, Wilson I. Integrative structural biology. *Science* 339, 913-915, 2013.

Comparative modeling by satisfaction of spatial restraints: MODELLER

3D GKITFYERGFQGHCYESDC-NLQP...

SEQ GKITFYERG---RCYESDCPNLQP...

A. Šali & T. Blundell. *J. Mol. Biol.* 234, 779, 1993.
J.P. Overington & A. Šali. *Prot. Sci.* 3, 1582, 1994.
A. Fiser, R. Do & A. Šali, *Prot. Sci.*, 9, 1753, 2000.

https://salilab.org/modeller/

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SEQ GKITFYERG---RCYESDCPNLQP...

1. Extract spatial restraints





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https://salilab.org/modeller/

A description of integrative structure determination



While it may be hard to live with generalization, it is inconceivable to live without it. Peter Gay, Schnitzler's Century (2002).

Integrative Modeling Platform (IMP) https://integrativemodeling.org



D. Russel, K. Lasker, B. Webb, J. Velazquez-Muriel, E. Tjioe, D. Schneidman, F. Alber, B. Peterson, A. Sali, PLoS Biol, 2012. R. Pellarin, M. Bonomi, B. Raveh, S. Calhoun, C. Greenberg, G.Dong.

- Diverse problems, so no one 'black box'
- "Mix and match" components for developing an integrative modeling protocol
- Open source (LGPL)
- Hosted on GitHub

Representation:

Scoring:

Atomic Rigid bodies Coarse-grained Multi-scale Symmetry / periodicity Multi-state systems

Density maps EM images Proteomics FRET Chemical and Cys cross-linking Homology-derived restraints SAXS Native mass spectrometry Statistical potentials Molecular mechanics forcefields Bayesian scoring Library of functional forms (ambiguity, ...)



Sampling:

Simplex Conjugate Gradients Monte Carlo Brownian Dynamics Molecular Dynamics Replica Exchange Divide-and-conquer enumeration

Analysis:

Clustering Chimera PyMOL PDB files Density maps







IMP kernel





IMP.algebra



IMP kernel





IMP.algebra





IMP kernel



IMP.em







IMP.algebra



IMP kernel





- Distinct functionality
- Developed separately
- Licensed differently
- Stable interfaces



IMP.algebra



IMP kernel





- Split into modules
- Distinct functionality
- Developed separately
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- Stable interfaces



IMP.algebra







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IMP.em

IMP.algebra Geometry, primitive shapes





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IMP.saxs

Handling of Small Angle X-ray (SAXS) data



IMP.algebra Geometry, primitive shapes







IMP.em Handling of electron microscopy (EM) experimental data

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Handling of Small Angle X-ray (SAXS) data



IMP.algebra Geometry, primitive shapes





- Sample is in solution
 - Pro: closer to its in vivo state
 - Con: rotationally averaged



Significant processing required to generate a 3D image





MODELLER

comparative modeling





MODELLER

comparative modeling



BioPython



handling of

sequence data



MODELLER

comparative modeling



BioPython



handling of

sequence data

Chimera/VMD visualization





MODELLER

comparative modeling



BioPython



handling of

sequence data

Chimera/VMD visualization



scikit-learn

clustering, machine

learning



MODELLER comparative modeling



BioPython



handling of

sequence data

Chimera/VMD visualization





numpy/scipy

matrix/linear algebra

scikit-learn clustering, machine

learning





MODELLER comparative modeling



BioPython



handling of

sequence data

Chimera/VMD visualization



etc.



numpy/scipy

matrix/linear algebra

scikit-learn clustering, machine

learning

Integrative Modeling Platform (IMP) https://integrativemodeling.org

- Each 'piece' is a Python class
- Most classes actually 'wrap' an underlying class in C++
 - C++ for speed, Python for flexibility
- Each module is a Python module, and C++ namespace
- IMP is usually used from Python, by writing a script
- A protocol is one or more Python scripts plus the input data

Example Python script

import IMP import IMP.algebra import IMP.core

m = IMP.Model()
Create two "untyped" Particles
p1 = IMP.Particle(m)
p2 = IMP.Particle(m)

"Decorate" the Particles with x,y,z attributes (point-like particles)

d1 = IMP.core.XYZ.setup_particle(p1) d2 = IMP.core.XYZ.setup_particle(p2)

Use some XYZ-specific functionality (set coordinates)

d1.set_coordinates(IMP.algebra.Vector3D(10.0, 10.0, 10.0)) d2.set_coordinates(IMP.algebra.Vector3D(-10.0, -10.0, -10.0)) print(d1, d2)

Harmonically restrain p1 to be zero distance from the origin

f = IMP.core.Harmonic(0.0, 1.0) s = IMP.core.DistanceToSingletonScore(f, IMP.algebra.Vector3D(0., 0., 0.)) r1 = IMP.core.SingletonRestraint(s, p1)

Harmonically restrain p1 and p2 to be distance 5.0 apart

f = IMP.core.Harmonic(5.0, 1.0)

- s = IMP.core.DistancePairScore(f)
- r2 = IMP.core.PairRestraint(s, (p1, p2))

Optimize the x,y,z coordinates of both particles with conjugate gradients

sf = IMP.core.RestraintsScoringFunction([r1, r2], "scoring function")
d1.set_coordinates_are_optimized(True)
d2.set_coordinates_are_optimized(True)
o = IMP.core.ConjugateGradients(m)
o.set_scoring_function(sf)
o.optimize(50)
print(d1, d2)

import IMP import IMP.algebra import IMP.core

Make IMP classes in the IMP kernel ('IMP') and IMP.algebra and IMP.core modules available

m = IMP.Model()
Create two "untyped" Particles
p1 = IMP.Particle(m)
p2 = IMP.Particle(m)

- Create a new Model object (an *instance* of the Model class) and assign it to the variable 'm'
 - An IMP Model is a container that holds knowledge of the entire system
- Create two Particles called 'p1' and 'p2'
 - A Particle is an abstract data container and can hold any number of attribute:value pairs, e.g.
 - xyz coordinates
 - mass
 - radius
 - pointers to other Particles, to represent a bond (two other particles), or hierarchy (parents, children)
 - element, residue/atom name, etc.

"Decorate" the Particles with x,y,z attributes (point-like particles) d1 = IMP.core.XYZ.setup_particle(p1) d2 = IMP.core.XYZ.setup_particle(p2)

Use some XYZ-specific functionality (set coordinates)
d1.set_coordinates(IMP.algebra.Vector3D(10.0, 10.0, 10.0))
d2.set_coordinates(IMP.algebra.Vector3D(-10.0, -10.0, -10.0))
print(d1, d2)

- A *decorator* lets us use a specific set of functionality on a Particle
 - 'd1' refers to the same underlying object as 'p1' but acts like a 3D point (IMP.core.XYZ class)
- set_coordinates() is a *method* of the XYZ class
 - IMP.algebra.Vector3D represents a 3D vector or coordinate

Harmonically restrain p1 to be zero distance from the origin

f = IMP.core.Harmonic(0.0, 1.0)

s = IMP.core.DistanceToSingletonScore(f, IMP.algebra.Vector3D(0., 0., 0.))

r1 = IMP.core.SingletonRestraint(s, p1)

- A Restraint is a term in our scoring function
- IMP.core.SingletonRestraint applies a Score to a single particle (p1 in this case)
- In turn, DistanceToSingletonScore calculates the Cartesian distance between a fixed point and p1, then uses a unary function to weight that distance
- Harmonic is a unary function that applies a simple harmonic spring
- In this way, we can very flexibly build our scoring function from basic building blocks

Harmonically restrain p1 and p2 to be distance 5.0 apart

- f = IMP.core.Harmonic(5.0, 1.0)
- s = IMP.core.DistancePairScore(f)
- r2 = IMP.core.PairRestraint(s, (p1, p2))

- Similarly, we make another Restraint called 'r2' that restrains the distance between two particles
- Usually distances are considered to be angstroms but this isn't required or enforced
Optimize the x,y,z coordinates of both particles with conjugate gradients
sf = IMP.core.RestraintsScoringFunction([r1, r2], "scoring function")
d1.set_coordinates_are_optimized(True)
d2.set_coordinates_are_optimized(True)
o = IMP.core.ConjugateGradients(m)
o.set_scoring_function(sf)
o.optimize(50)
print(d1, d2)

- Finally, we make a simple scoring function 'sf' that's just the sum of the two harmonic restraints
- We find the minimum of the function using up to 50 steps of conjugate gradients
 - At each step the algorithm will try to reduce the value of the scoring function by changing the coordinates of d1 and/or d2

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So let's run it…

Example Python script

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- s = IMP.core.DistancePairScore(f)
- r2 = IMP.core.PairRestraint(s, (p1, p2))

```
# Optimize the x,y,z coordinates of both particles with conjugate gradients
sf = IMP.core.RestraintsScoringFunction([r1, r2], "scoring function")
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d2.set_coordinates_are_optimized(True)
o = IMP.core.ConjugateGradients(m)
o.set_scoring_function(sf)
o.optimize(50)
print(d1, d2)
```

- So let's run it…
- Very flexible, but all we've done here is move two points!

Higher level interfaces



- In practice, scripts for "real" modeling problems would be too long and unwieldy to write this way
- Most usage of IMP is via simpler (but less 'expressive') interfaces

Chimera tools/ web services



- AllosMod: modeling of ligand-induced protein dynamics, allostery
- FoXS: fast SAXS profile computation with Debye formula



- FoXSDock: macromolecular docking with SAXS Profile
- SAXSMerge: automated statistical method to merge SAXS profiles from different concentrations and exposure times



Pose&Rank: scoring of protein-ligand complexes



Domain-specific applications

- Command line tools
- Generally, similar functionality to web services, but running locally



PMI

- Just another IMP module (IMP.pmi)
- A meta language for modeling
- We still write Python scripts, but...
 - Many protocols (e.g. replica exchange) already packaged up nicely for us
 - Refer to biological units rather than individual particles
 - Publication-ready plots are more or less automatic
- Regular IMP objects are constructed, so an advanced user can always customize things using the full collection of IMP classes if PMI is insufficient
- Today we will use PMI to model the stalk of the RNA Polymerase II complex: https://github.com/salilab/imp_tutorial/

Reproducibility/Deposition



Reproducibility/Deposition



Reproducibility/Deposition

- Store protocol in GitHub so others can run it, improve it, modify it
- Document!
- Automated tests
- DOI (Zenodo, Figshare)



https://pdb-dev.rcsb.rutgers.edu/ https://integrativemodeling.org/systems/

Example: Nup84



Mol Cell Proteomics 13, 2927-2943, 2014

Cross-linking coupled with mass spectrometry (CX-MS)



Output, essentially, is a list of proximal residue pairs (again, after processing)

Note: spectra can identify multiple cross-links (ambiguity)

Installation

- We need installed
 - numpy and scipy for matrix and linear algebra
 - scikit-learn for k-means clustering
 - matplotlib for plotting results
 - Chimera for visualization of results
 - IMP itself
- Easiest way is to install Anaconda Python, then run:

conda config --add channels salilab conda install imp numpy scipy scikit-learn matplotlib

 Get the tutorial files from GitHub: <u>https://github.com/salilab/imp_tutorial/</u>

Integrative Structure Modeling of RNA Polymerase II stalk

- RNA Pol II is a eukaryotic complex that catalyzes DNA transcription to synthesize mRNA strands.
- Eukaryotic RNA polymerase II contains 12 subunits, Rpb1 to Rpb12.
- The yeast RNA Pol II dissociates into a 10-subunit core and a Rpb4/Rpb7 heterodimer.
- Rpb4 and Rpb7 are conserved from yeast to humans, and form a stalk-like protrusion extending from the main body of the RNA Pol II complex.

Integrative Structure Modeling of RNA Polymerase II stalk

- We want to determine the localization of two subunits of the yeast RNA Polymerase II, Rpb4 and Rpb7 (stalk), hypothesizing that we know already the structure of the remaining 10-subunit complex.
- This example utilizes:
 - chemical cross-linking coupled with mass spectrometry (CX-MS),
 - negative-stain electron microscopy (EM),
 - x-ray crystallography data



Get tutorial files from GitHub

• Let's get started by getting the main modeling script running while we look at what it's doing:

cd imp_tutorial/rnapolii/modeling
python modeling.py --test

- "Real" modeling will take hours, so we're running in 'test' mode which generates only 50 frames (rather than 20,000)
- The script covers the first 3 steps of integrative modeling



Data for yeast RNA Polymerase II

- The rnapolii/data folder contains:
 - Sequence information (FASTA files for each subunit)
 - Electron density maps (.mrc, .txt files)
 - Structure from x-ray crystallography (PDB file)
 - Chemical crosslinking datasets (two data sets, one from Al Burlingame's lab, and another from Juri Rappsilber's lab)



FASTA file

1WCM.fasta.txt:

>1WCM:A

MVGQQYSSAPLRTVKEVQFGLFSPEEVRAISVAKIRFPETMDETQTRAKIGG LNDPRLGSIDRNLKCQTCQEGMNECPGHFGHIDLAKPVFHVGFIAKIKKVCE CVCMHCGKLLLDEHNELMRQALAIKDSKKRFAAIWTLCKTKMVCETDVPSED

• • •

>1WCM:B

MSDLANSEKYYDEDPYGFEDESAPITAEDSWAVISAFFREKGLVSQQLDSFN QFVDYTLQDIICEDSTLILEQLAQHTTESDNISRKYEISFGKIYVTKPMVNE SDGVTHALYPQEARLRNLTYSSGLFVDVKKRTYEAIDVPGRELKYELIAEES

- defines two chains with unique IDs of 1WCM:A and 1WCM:B respectively
- 12 chains in total, A through L

Gathering information
\checkmark
Designing model representation and evaluation
\checkmark
Sampling models
\checkmark
Analyzing models and information

Electron density map

emd_1883.map.mrc experimental map of entire complex at 20.9Å resolution

and covariance matrix of each Gaussian used to approximate the

original EM density can be seen in *emd_1883.map.mrc.gmm.50.txt*



X-ray structures

1WCM.pdb high resolution coordinates for all 12 chains of RNA Pol II



Chemical cross-links

polii_xlinks.csv and *polii_juri.csv*: multiple comma-separated columns; four of these specify the protein and residue number for each of the two linker residues:

```
prot1, res1, prot2, res2
Rpb1, 34, Rpb1, 49
Rpb1, 101, Rpb1, 143
Rpb1, 101, Rpb1, 176
```

The length of the DSS/BS3 cross-linker reagent, 21Å, will be specified later in the modeling script.



Model representation in IMP

Representation is defined by all the variables that need to be determined based on input information (e.g. points, spheres, ellipsoids, and 3D Gaussian density functions).

We use *spherical beads* and *3D Gaussians*. The *spatial restraints* will be applied to individual resolution scales as appropriate.

Beads and Gaussians of a given domain are arranged into either a rigid body or a flexible string.





Handling of missing structure

- Even though we have X-ray structures, not all residues were resolved (yellow regions)
- Would be over-interpretation of the data to try to represent this at high resolution
- Use low resolution beads (20 residues per bead) instead here
- Treat high resolution regions as rigid bodies, allow low resolution regions to move (floppy bodies)









IMP topology file

rnapolii/data/topology.txt The topology file stores the basic information needed to create a structural model in IMP.



Evaluation

- At this point we need to create our scoring function, by which the individual structural models will be scored based on the input data
- A sum of individual restraints
- Each restraint maps to one of our input experiments or other physical/statistical information



Sequence connectivity restraint

- We know that residues that are adjacent in sequence will also be close in space, due to the peptide bond
- We should enforce this in our modeling by adding simple harmonic restraints between beads
- PMI handles this automatically based on the FASTA file
 - nothing needed in our script



Excluded volume restraint

- We also know that one protein cannot occupy the same space as another
- The excluded volume restraint is calculated at resolution 20 (20 residues per bead)
 - Faster to evaluate, but more approximate
- We're maintaining a list of 'output objects', and this will be one of them
 - Statistics on such objects (e.g. whether the score is satisfied) will be collected during the modeling



Crosslinking restraints

Gathering

information

Designing model

representation and evaluation

Sampling

models

- Restrain residue pairs based on the crosslinks files
- Residue-level information, so apply at resolution 1
- Length of cross linker given here
- The restraint is Bayesian with ψ and σ noise parameters
 - We'll need to sample those parameters later at the same time as the xyz coordinates (sampleobjects)

```
xl1 = IMP.pmi.restraints.crosslinking.ISDCrossLinkMS(representation,
                                     datadirectory+'polii xlinks.csv',
                                     length=21.0,
                                      slope=0.01,
                                      columnmapping=columnmap,
                                     resolution=1.0,
                                                                               Analyzing models
                                     label="Trnka",
                                                                                and information
                                      csvfile=True)
xl1.add to model()
sampleobjects.append(xl1)
outputobjects.append(xl1)
```

EM restraint

- We're using a density overlap function to compare the GMM approximation of our model (em_components) with that of the EM map itself (target_gmm_file)
 - scale_to_target_mass ensures the total masses of model and map are identical
 - slope: nudge model closer to map when far away
 - weight: heuristic, needed to calibrate the EM restraint with the other terms.



Sampling

 We're going to use Monte Carlo to sample (not minimize) our system (generate many models that satisfy the data)



Thus, need to define a set of movers

Monte Carlo setup

- Bead movers: simple 3D translation, sampled linearly up to a given max value
- Rigid body movers: 3D translation and rotation
- Also we define here how to move our rigid bodies
- (Remember that we also 'move' non-Cartesian parameters for our Bayesian restraints)



Rigid body movers



Rigid body movers

rigid_bodies defines the components that will be moved as rigid bodies (in this case, the parts of Rpb4 and Rpb7 for which we have X-ray structure). Unstructured regions will move as flexible beads.




super_rigid_bodies defines sets of rigid bodies and beads that will move together in an additional Monte Carlo move.



Gathering

super_rigid_bodies defines sets of rigid bodies and beads that will move together in an additional Monte Carlo move.



Gathering information

Gathering

information

Sampling

models

chain_of_super_rigid_bodies sets additional Monte Carlo movers along the connectivity chain of a subunit. It groups sequenceconnected rigid domains and/or beads into overlapping pairs and triplets. Each of these groups will be moved rigidly. This mover helps to sample more efficiently complex topologies, made of several rigid bodies, connected by flexible linkers.



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Designing model representation and evaluation

Gathering

information

Sampling models

 \checkmark

Analyzing models and information

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Designing model representation and evaluation

Sampling models

Analyzing models and information

Gathering

information

Sampling

Gathering information

- Finally, we run the Monte Carlo sampling itself
- Technically this is replica exchange but with only one replica (we're not running in parallel with MPI)

```
mc1=IMP.pmi.macros.ReplicaExchange0(m,
                                                                                    Designing model
                    representation,
                                                                                     representation
                    monte carlo sample objects=sampleobjects,
                    output objects=outputobjects,
                                                                                     and evaluation
                    crosslink restraints=[xl1,xl2],
                    monte carlo temperature=1.0,
                    simulated annealing=True,
                    simulated annealing minimum temperature=1.0,
                    simulated annealing maximum temperature=2.5,
                                                                                        Sampling
                    simulated annealing minimum temperature nframes=200,
                                                                                        models
                    simulated annealing maximum temperature nframes=20,
                    replica exchange minimum temperature=1.0,
                    replica exchange maximum temperature=2.5,
                    number of best scoring models=100,
                    monte carlo steps=num mc steps,
                    number of frames=num frames,
                                                                                     Analyzing models
                    global output directory="output")
                                                                                      and information
```

Running the script

python modeling.py autobuild_model: constructing Rpb1 from pdb ../data/./1WCM_map_fitted.pdb and chain A autobuild_model: constructing fragment (1, 1) as a bead autobuild_model: constructing fragment (2, 186) from pdb autobuild_model: constructing fragment (187, 194) as a bead autobuild_model: constructing fragment (195, 1081) from pdb autobuild_model: constructing fragment (1082, 1091) as a bead autobuild_model: constructing fragment (1092, 1140) from pdb autobuild_model: constructing Rpb1 from pdb ../data/./1WCM_map_fitted.pdb and chain A autobuild_model: constructing fragment (1141, 1176) from pdb autobuild_model: constructing fragment (1177, 1186) as a bead autobuild_model: constructing fragment (1187, 1243) from pdb autobuild_model: constructing fragment (1244, 1253) as a bead

•••

Adding sequence connectivity restraint between Rpb4_1-3_bead and Rpb4_4_13_pdb of distance 14.4 Adding sequence connectivity restraint between Rpb4_74_76_pdb and Rpb4_77-96_bead of distance 14.4 Adding sequence connectivity restraint between Rpb4_77-96_bead and Rpb4_97-116_bead of distance 14.4 Adding sequence connectivity restraint between Rpb4_97-116_bead and Rpb4_117_bead of distance 14.4

•••

generating a new crosslink restraint

ISDCrossLinkMS: generating cross-link restraint between ISDCrossLinkMS: residue 358 of chain Rpb2 and residue 246 of chain Rpb2 ISDCrossLinkMS: with sigma1 1.000000 sigma2 1.000000 psi 0.05 ISDCrossLinkMS: between particles Rpb2_358_pdb and Rpb2_246_pdb

•••

- --- frame 1 score 4814598.44759
- --- writing coordinates
- --- frame 2 score 3527090.92513
- --- writing coordinates
- --- frame 3 score 2662180.99705
- --- writing coordinates
- --- frame 4 score 2021182.74211



Output data



Analyzing models

and information

- Note that PDB is not well suited for non-atomic structures
- IMP uses its own format (RMF) for coarse-grained structures
- PDB's next generation file format (mmCIF) will natively support these structures

Analysis

- In the analysis stage we cluster (group by similarity) the sampled models to determine high-probability configurations. Comparing clusters may indicate that there are multiple acceptable configurations given the data.
- Cluster Precision: Determining the within-group precision and between-group similarity via RMSD
- Cluster Accuracy: Fit of the calculated clusters to the true (known) solution
- Sampling Exhaustiveness: Qualitative and quantitative measurement of sampling completeness



Clustering

- A simple clustering protocol is shown in rnapolii/analysis/clustering.py
- Simply run with python clustering.py --test
- k-means clustering after discarding bad-scoring models using all-against-all comparisons of Rpb4 and Rpb7 positions

 Also generates localization densities - maps showing the probability of finding each protein at each point in space - that give a good idea of the "spread" of all models in the cluster



Clustering output

- Outputs won't look great, since we built only 50 models (many of which were discarded by prefiltering)
- Outputs shown here are from a much longer run (overnight) with 2 clusters requested
- Typically cluster representatives and localization densities are reported in publications

🔻 📄 kmeans_100_2	
cluster.0	
0.pdb	
0.rmf3	
1.pdb	
1.rmf3	
2.pdb	
2.rmf3	
3.pdb	
3.rmf3	
4.pdb	
4.rmf3	
5.pdb	
5.rmf3	
Rpb4.mrc	
Rpb7.mrc	
stat.out	
cluster.1	
a dist_matrix.pdf	



Clustering output

 Distance matrix (dist_matrix.pdf) and dendrogram of the models after being grouped into clusters. The matrix should show the requested number of clusters with much lower within-cluster than between-cluster distance. If this is not the case, then perhaps too many clusters were chosen.



Gathering

information

Clustering output

- Localization densities (*.mrc files)
- The localizations are quite narrow and close to native



Other analysis

- Cluster precision (precision_rmsf.py)
 - shows spread of each cluster
- Accuracy evaluation (accuracy.py)
 - compare against known structure
- Sampling exhaustiveness: how can we be sure we've done enough sampling?
 - a variety of methods exist, not covered here today
 - for example, two independent runs should sample from the same distribution - can test statistically, or by comparing clusters
 - can also model leaving out some of the data (jackknife)
 - validate by comparison with data not used in the modeling
 - emergence of patterns not expected by chance



Iteration

- Once we're satisfied that our sampling is complete, we can use the output to suggest new experiments
- For example
 - a high value for a subunit precision suggests we need more intramolecular data (such as crosslinks)
 - clusters where the configuration of certain subunits is ambiguous suggests the need for more protein-protein interaction data involving those subunits
 - e.g. in this case crosslinks were sufficient to get Rpb4 and Rpb7 the 'right way round' in the stalk, but the EM map alone would likely not be

Gathering information

Conclusion

- Integrative modeling provides structural models where individual experimental methods fail
- The Integrative Modeling Platform (IMP) is a toolbox for solving integrative modeling problems
- Generate multi-scale (also multi-state, time ordered) ensembles of models consistent with multiple sources of information

https://integrativemodeling.org/

D. Russel, K. Lasker, B. Webb, J. Velazquez-Muriel, E. Tjioe, D. Schneidman,F. Alber, B. Peterson, A. Sali, PLoS Biol, 2012.R. Pellarin, M. Bonomi, B. Raveh, S. Calhoun, C. Greenberg, G.Dong.



Designing model representation and evaluation



Sampling models



Analyzing models and information